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 April 1995 **The VLDB Journal -- The International Journal on Very Large Data Bases**, Volume 4 Issue 2

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C. H. Papadimitriou, D. Suciu, V. Vianu
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Proceedings of the fifteenth ACM SIGACT-SIGMOD-SIGART symposium on Principles of database systems
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Peter Baumann
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- ¹⁹ [The VLSI Complexity of Selected Graph Problems](#)
Joseph Já Já
March 1984
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Dana H. Ballard

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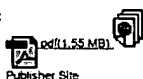
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 calculus of operations that generalizes standard **boolean** operations on shapes such as union, us information about the topology of the collision **region** between the barrier and the robot (its in two dimensions. They augmented the standard **boundary** representation of planar shapes via polygons or
robotics.stanford.edu/~ramkumar/papers/3d-conv.ps.gz

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 plane to be polygons. It turns out that P forms a **Boolean** algebra. In this **Boolean** algebra, the product of obtained by adopting a spatial ontology in which **regions**, not points, are the primitive entities. This that part of the plane lying outside it and its **boundary** and the sum of two polygons is the polygon
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www.research.att.com/~krishnas/MY_PAPERS/IFIP96.ps.gz

[Formalizing Commonsense Topology: The - Calculus](#) Nicholas Mark (Correct)
 other. Next, we establish that if an 1 Quasi-**Boolean** because there is no 'zero' **region**. Extent are not: every surface has two sides if two **regions** occupy the same part of space, they include the relations (e.g. partial overlap, contact at the **boundary**) between specific spatially extended entities,
agora.leeds.ac.uk/scs/doc/srg/AlandMsymp.ps

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 point-set may be implicitly represented as the **B** **lean** XOR of unbounded polyhedral "stripes" of

is shot from either the interior or the exterior **region**. This result is actually dimension-independent,
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representations of solids, and defined regularized **B** lean operations by merging BSP trees [7]
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From Polyline to Polygon via XOR tree - Baldazzi, Paoluzzi (1996) (Correct)
that each such polygon can be expressed as the **Boolean** XOR of unbounded quadrilateral stripes,
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Surface/surface Intersections: A Three States.. - S. Foufou, J.M. Brun, A.. (Correct)
the first point in the context of solids algebra (**Boolean** operators) for which it is of utmost importance
by Sederberg and Nishita [SN90] and defined as the **region** between two parallel lines which bounds a B'ezier
fuzzy face, a fuzzy line is calculated for each **boundary** curve of the surface. A fuzzy face (figure 3) is
bat710.univ-lyon1.fr/~foufou/papers_ps/london.ps.Z

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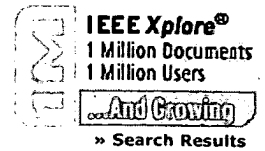
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Antony, R. T.;
 Proceedings of the IEEE , Volume: 85 , Issue: 1 , Jan. 1997
 Pages:39 - 53

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2 An adaptive threshold strategy for soft decision Viterbi decoding

Antony, R.; Ilow, J.;
 Electrical and Computer Engineering, 2003. IEEE CCECE 2003. Canadian Conference on , Volume: 3 , 4-7 May 2003
 Pages:1659 - 1662 vol.3

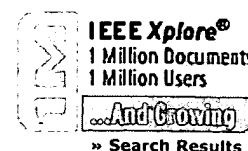
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Kahng, A.B.; Robins, G.; Singh, A.; Zelikovsky, A.;

Computer-Aided Design of Integrated Circuits and Systems, IEEE Transactions on , Volume: 18 , Issue: 4 , April 1999
Pages:445 - 462
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2 The segmentation of cursive handwriting: an approach based on off-line recovery of the motor-temporal information

Plamondon, R.; Privitera, C.M.;

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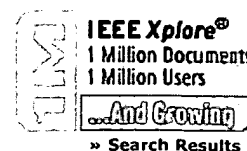
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